



Predictive and Prescriptive Analytics toward Optimizing Wildfire Suppression

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Acknowledgements: Ryne Reger and Erwin Deng



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An ever-growing impact of wildfires

Los Angeles Times

January 7, 2025

Pacific Palisades fire explodes to nearly 3,000 acres as thousands of residents flee, homes are lost

Los Angeles Times

January 9, 2025

Death toll in Los Angeles wildfires rises to 10, officials report

The New York Times

January 11, 2025

Winds Intensify in L.A. as Wildfire Death Toll Rises to 16

"We are in a 'triage mode' where our primary focus must be on fires that threaten communities and infrastructure."

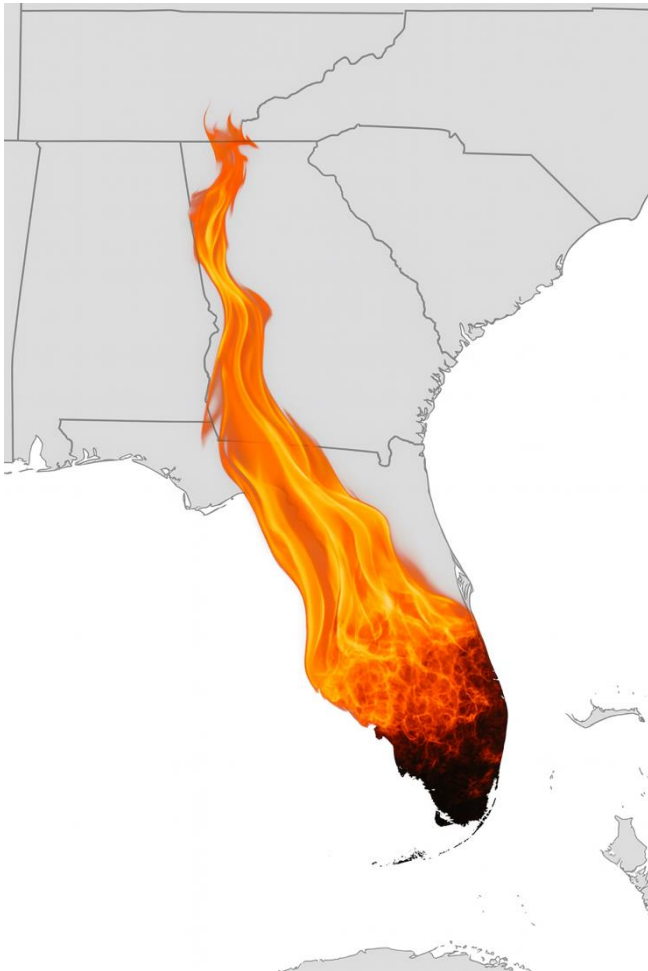
- Randy Moore, Chief
US Forest Service



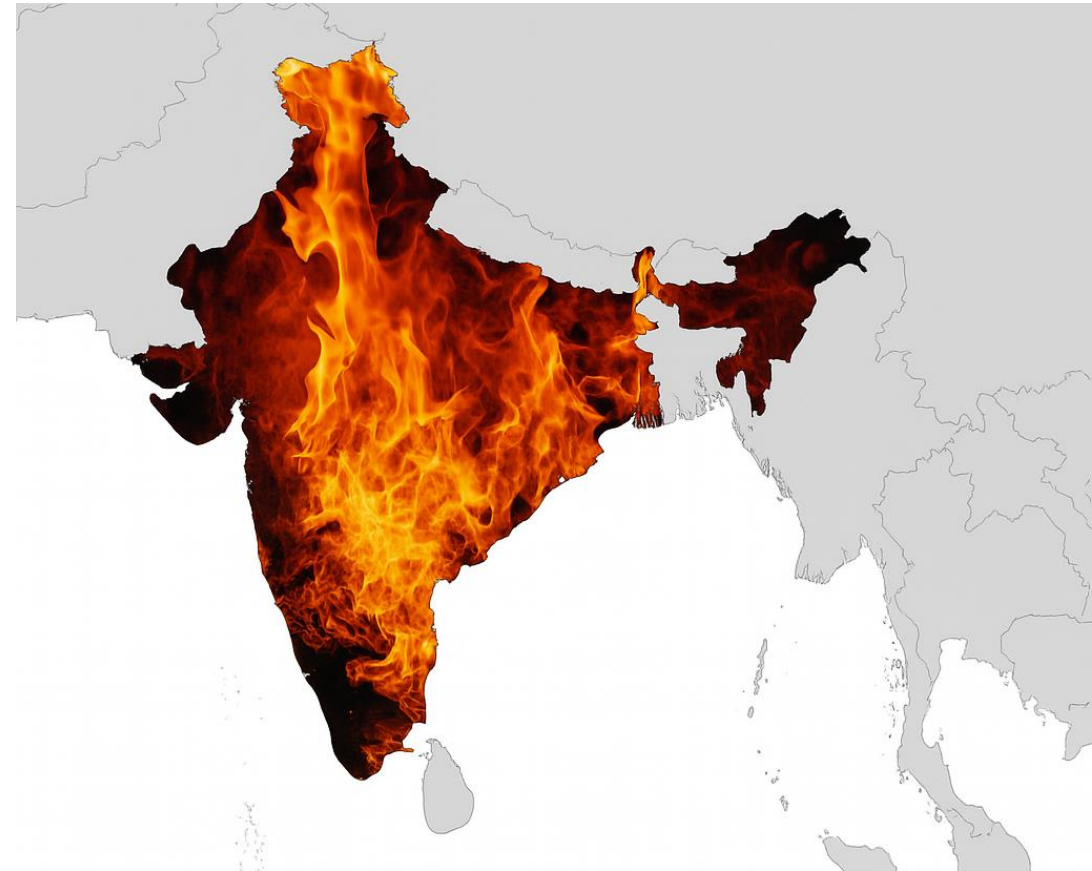
Current Preparedness Level



In 2024, in the US, ~65,000 wildfires burned **~9 million acres.**



In 2024, wildfires globally burned approximately **~900 million acres** (3.88 million square kilometers).





Simultaneous triage and routing

Crew routing



Fire triage



Simultaneous triage and routing

Crew routing

- Vehicle routing-scheduling dynamics to attend fires in a spatial-temporal environment
- Routing considerations
 - Travel cost and time
 - Acute and accumulated fatigue
 - Policies and regulations
- **Endogenous demand:**
Fires grow while unattended

Fire triage

- Triage dynamics to prioritize high-risk fires, and delay suppression efforts elsewhere
- Triage considerations
 - Damage and spread risk
 - Suppression difficulty
- **Heterogeneous switching costs** over a wide geography

Contributions

Branch-and-price-and-cut algorithm for prescriptive wildfire analytics

Optimization modeling

Two-sided set-partition formulation to model fire spread dynamics and crew routes on time-expanded networks

Optimization algorithm

Two-sided branch-and-price-and-cut, with augmented GUB cutting planes, dual-aware branching, and primal heuristics

Computational results

Computational improvements in medium-scale problems, and provably high-quality solutions in large-scale problems

Data-driven case study

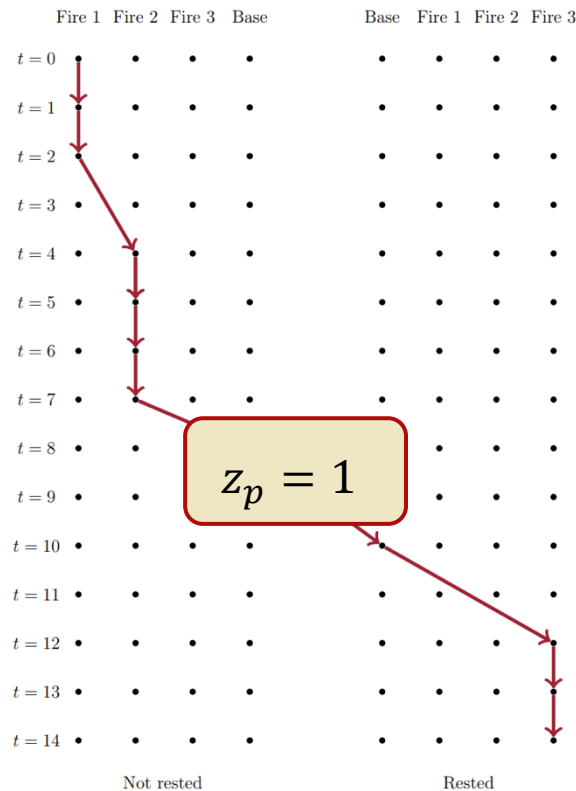
Data-driven impact: double machine learning to estimate the wildfire suppression dynamics, and benefits of optimization

OPTIMIZING WILDFIRE SUPPRESSION



Time-expanded network representation

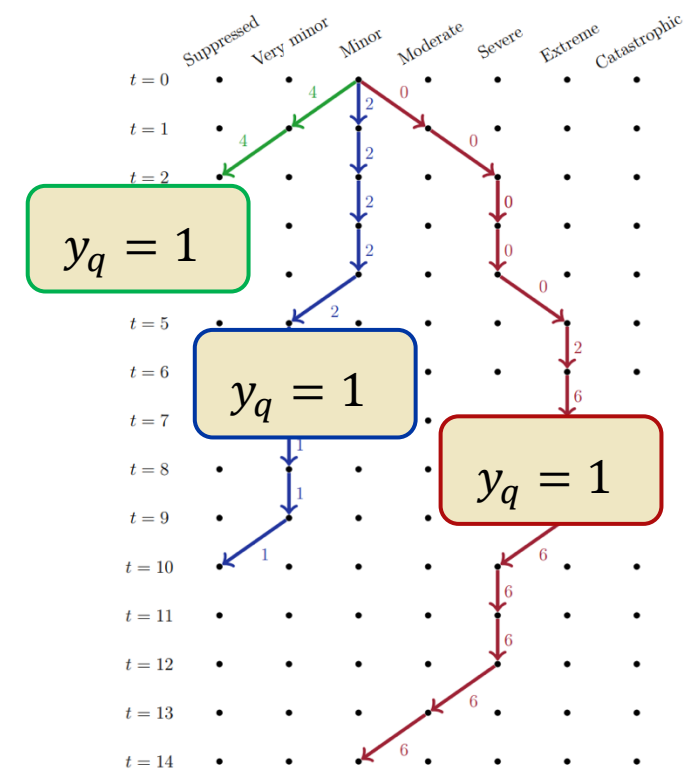
Crews: time-space-rest network



We model **full crew work plans** and **full fire evolution plans**.

We use **linking constraints** that tie these two networks together.

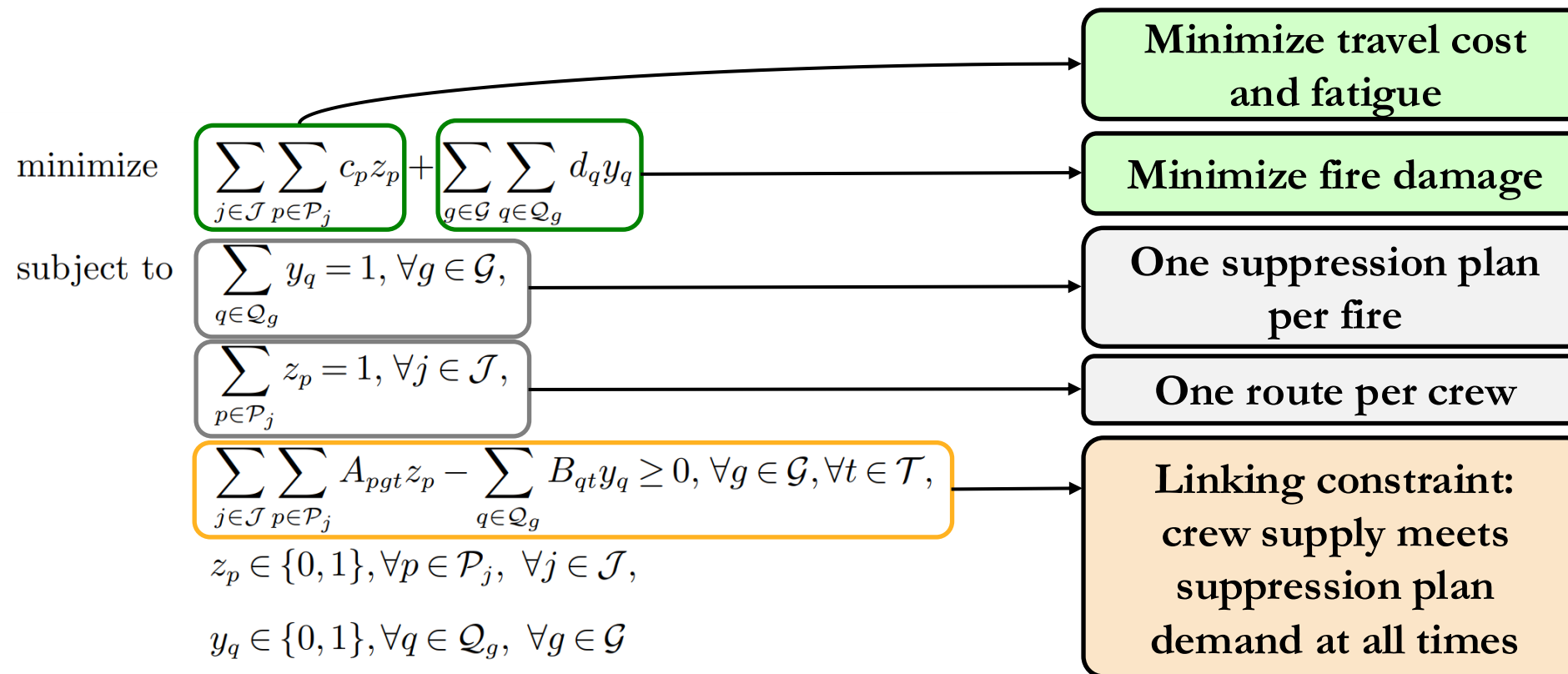
Fires: time-state network



Two-sided set partitioning formulation

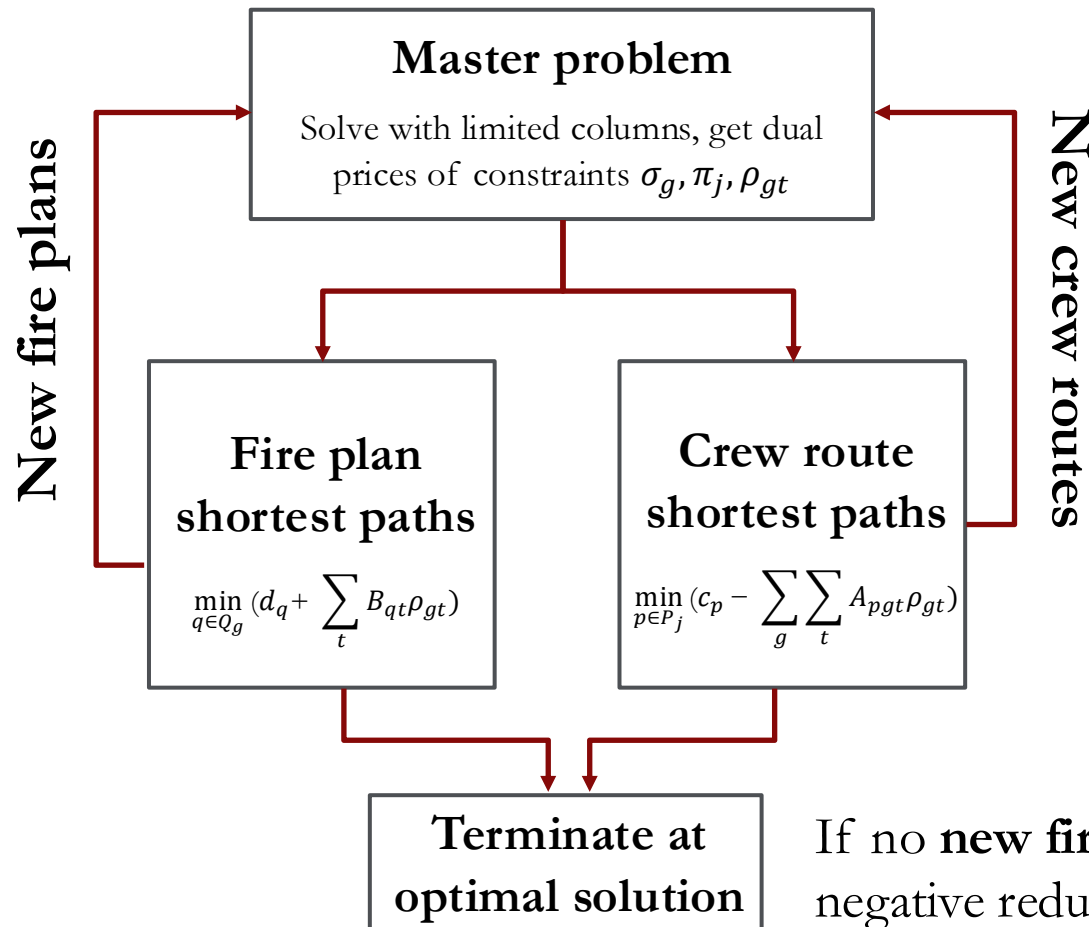
We avoid modeling individual arcs explicitly and instead model **entire plans & routes** as decision variables.

Proposition: The formulations are equivalent, with the same relaxations



Two-sided column generation

We solve the master problem using only a subset of all possible fire plans and crew routes and add more iteratively.



The two-sided structure induces a decomposition by fire and by crew in the pricing problems

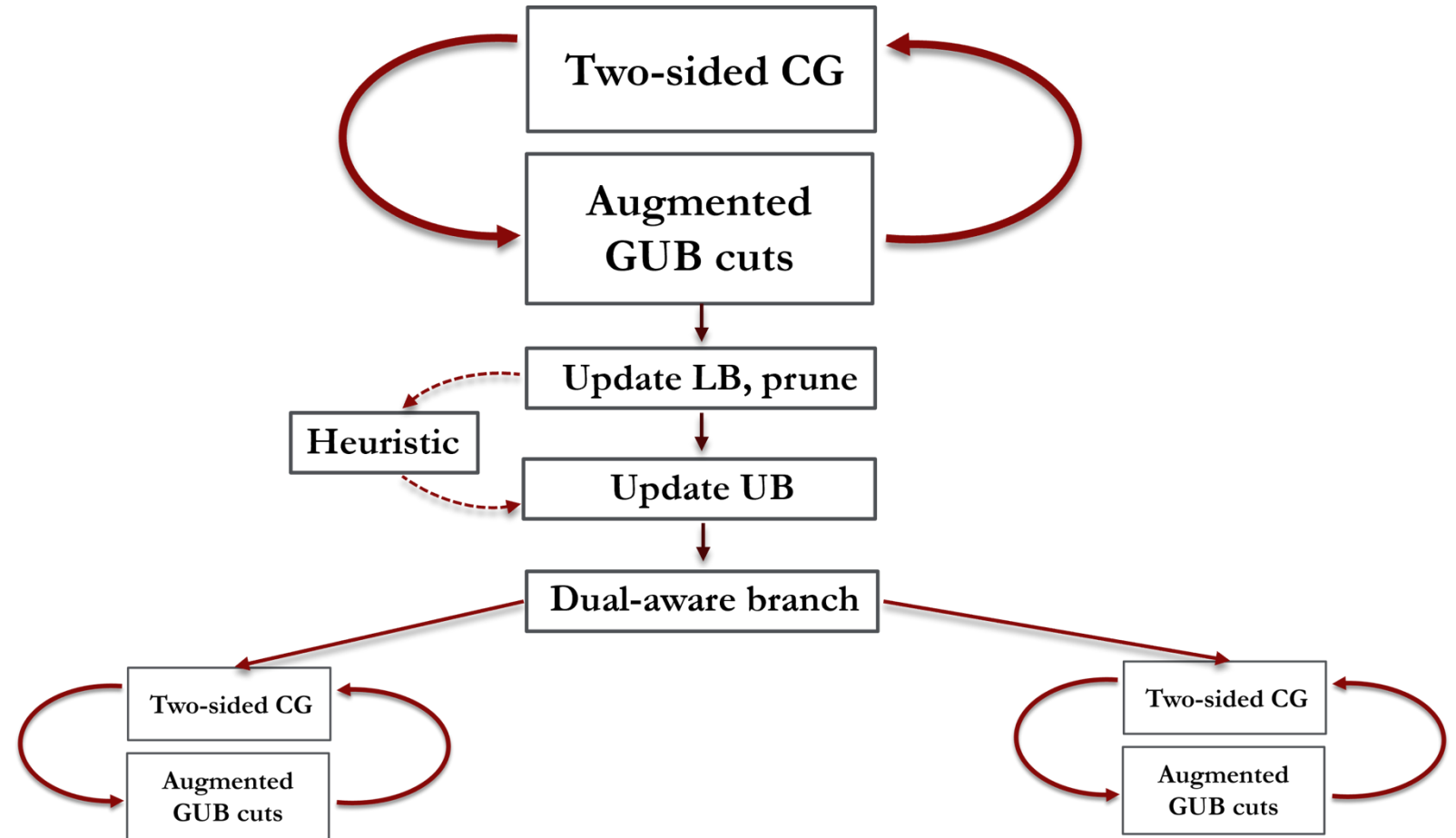
Key idea: ρ_{gt} incorporates local information into pricing problems

If no new fire plan or crew route has negative reduced cost, we're done.

Putting it all together: Branch-and-price-and-cut

Key idea:

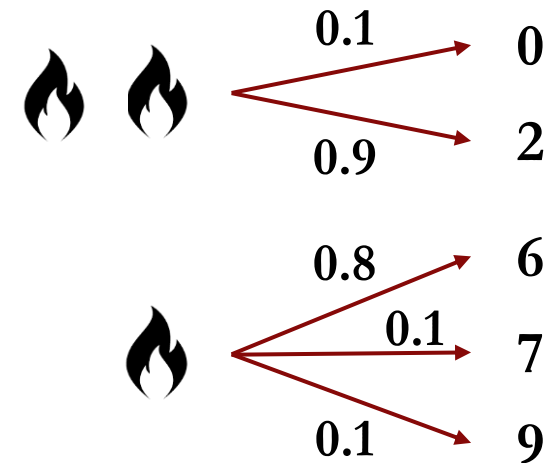
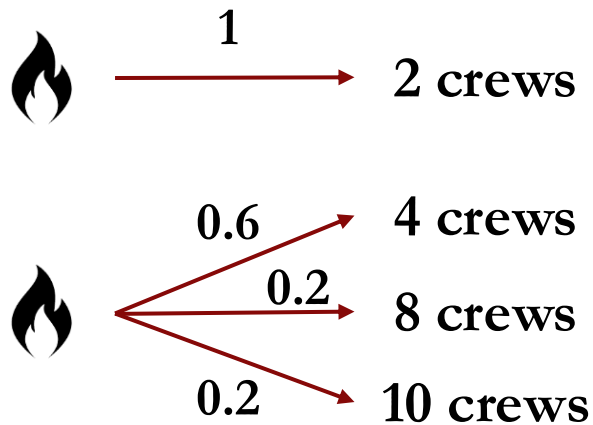
- We solve a smaller problem,
- **Generate** better fire plans and crew routes on demand,
- **Tighten** the problem with cuts,
- Use **heuristic** to find **feasible** integer solution,
- Intelligently **branch** when needed.



Theorem: The algorithm converges finitely to an optimal solution

Cutting planes: 10-crew fire suppression plan example

Challenge: During master LP relaxation, the solver may pick **fractions of different fire suppression plans.**



$$\sum_{q \in Q_1} \mathbb{1}[B_{qt} \geq 2]y_q + \sum_{q \in Q_2} \mathbb{1}[B_{qt} \geq 10]y_q \leq 1$$

This is a **GUB cut**: “You can’t mix these plans because there’s no way to round them into a valid integer solution.”

$$\frac{1}{2} \sum_{q \in Q_1} \mathbb{1}[B_{qt} \geq 2]y_q + \frac{1}{2} \sum_{q \in Q_2} \mathbb{1}[B_{qt} \geq 2]y_q + \frac{1}{2} \sum_{q \in Q_3} \mathbb{1}[7 \leq B_{qt} \leq 8]y_q + \sum_{q \in Q_3} \mathbb{1}[B_{qt} \geq 9]y_q \leq 1$$

Cutting planes for LP: robust cuts

- Generalized upper-bound cover cuts (Wolsey)

$$\sum_{g \in \mathcal{G}_u} \sum_{q \in \mathcal{Q}_g} \mathbb{1}[B_{qt} \geq D_{ug}] y_q + \sum_{j \in \mathcal{J}_u} \sum_{p \in \mathcal{P}_j} \mathbb{1} \left[\sum_{g \in \mathcal{G}_u} A_{pgt} = 0 \right] z_p \leq |\mathcal{G}_u| + |\mathcal{J}_u| - 1$$

- **Augmented GUB cover cuts**

- Cut-generating linear program to generate augmented GUB cover cuts
- Detects combinations of fire plans that are allowed in the LP and not eliminated by GUB cuts

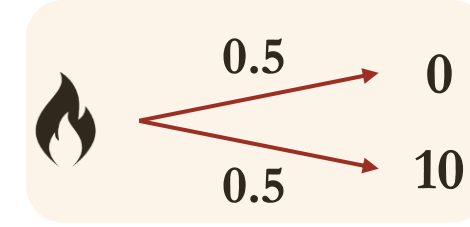
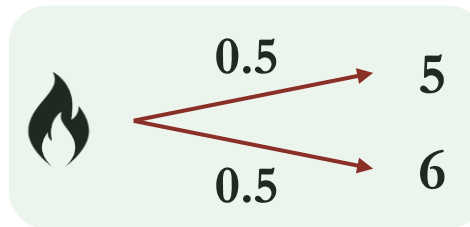
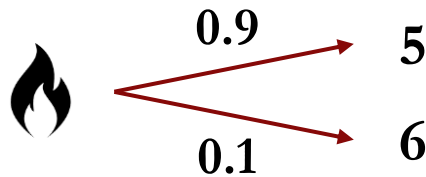
$$\sum_{g \in \mathcal{G}_u} \sum_{q \in \mathcal{Q}_g} \sum_{d=0}^J \mathbb{1}[B_{qt} = d] \delta_{ugd} y_q + \sum_{j \in \mathcal{J}_u} \sum_{p \in \mathcal{P}_j} \mathbb{1} \left[\sum_{g \in \mathcal{G}_u} A_{pgt} = 0 \right] z_p \leq |\mathcal{J}_u| + K_u$$

These cuts dramatically improve relaxation strength and reduce the number of branches needed.

Branching: variable selection

Once the LP+cuts are as tight as possible, we still may need to **branch** to get an integer solution.

- Most fractional branching vs. maximum-variance branching



- **Dual-aware maximum variance variable selection:** leverage linking dual prices to identify “high-leverage” ambiguous variables (how valuable a crew is at that time and place).

$$\left(\sum_{q \in \mathcal{Q}_g} B_{qt}^2 y_q^* \right) - \left(\sum_{q \in \mathcal{Q}_g} B_{qt} y_q^* \right)^2 \longrightarrow \left(\sum_{q \in \mathcal{Q}_g} (B_{qt} \rho_{gt}^*)^2 y_q^* \right) - \left(\sum_{q \in \mathcal{Q}_g} B_{qt} \rho_{gt}^* y_q^* \right)^2$$

Theorem: (Dual-aware) maximum-variance branching converges finitely to integer solution, whereas fractional branching may not.

Branch-and-price-and-cut algorithm

Benefits of augmented GUB cuts

Benefits of dual-aware branching

Benefits of primal heuristic

Crews	Fires	Cuts	Heuristic	Branching	CPU	Opt. gap	UB	LB	Nodes	Columns
20	6	False	False	MF	1,200	—	—	1.00	4,757	600,982
				D-MV	288	0.00%	1.00	1.00	1,439	152,280
			True	MF	1,200	1.08%	1.01	1.00	4,712	623,146
				D-MV	313	0.00%	1.00	1.00	1,437	170,650
		True	False	MF	1,200	—	—	1.00	660	134,921
				D-MV	229	0.00%	1.00	1.00	83	24,118
			True	MF	1,200	0.65%	1.01	1.00	642	137,101
				D-MV	179	0.00%	1.00	1.00	49	17,415
30	9	False	False	MF	1,200	—	—	1.00	1,832	410,675
				D-MV	1,200	—	—	1.01	1,902	493,830
			True	MF	1,200	4.58%	1.05	1.00	1,681	378,326
				D-MV	1,200	2.84%	1.04	1.02	1,682	433,931
		True	False	MF	1,200	—	—	1.00	101	55,575
				D-MV	1,200	—	—	1.02	135	66,109
			True	MF	1,200	3.57%	1.04	1.00	52	58,285
				D-MV	1,200	2.59%	1.04	1.01	62	55,285

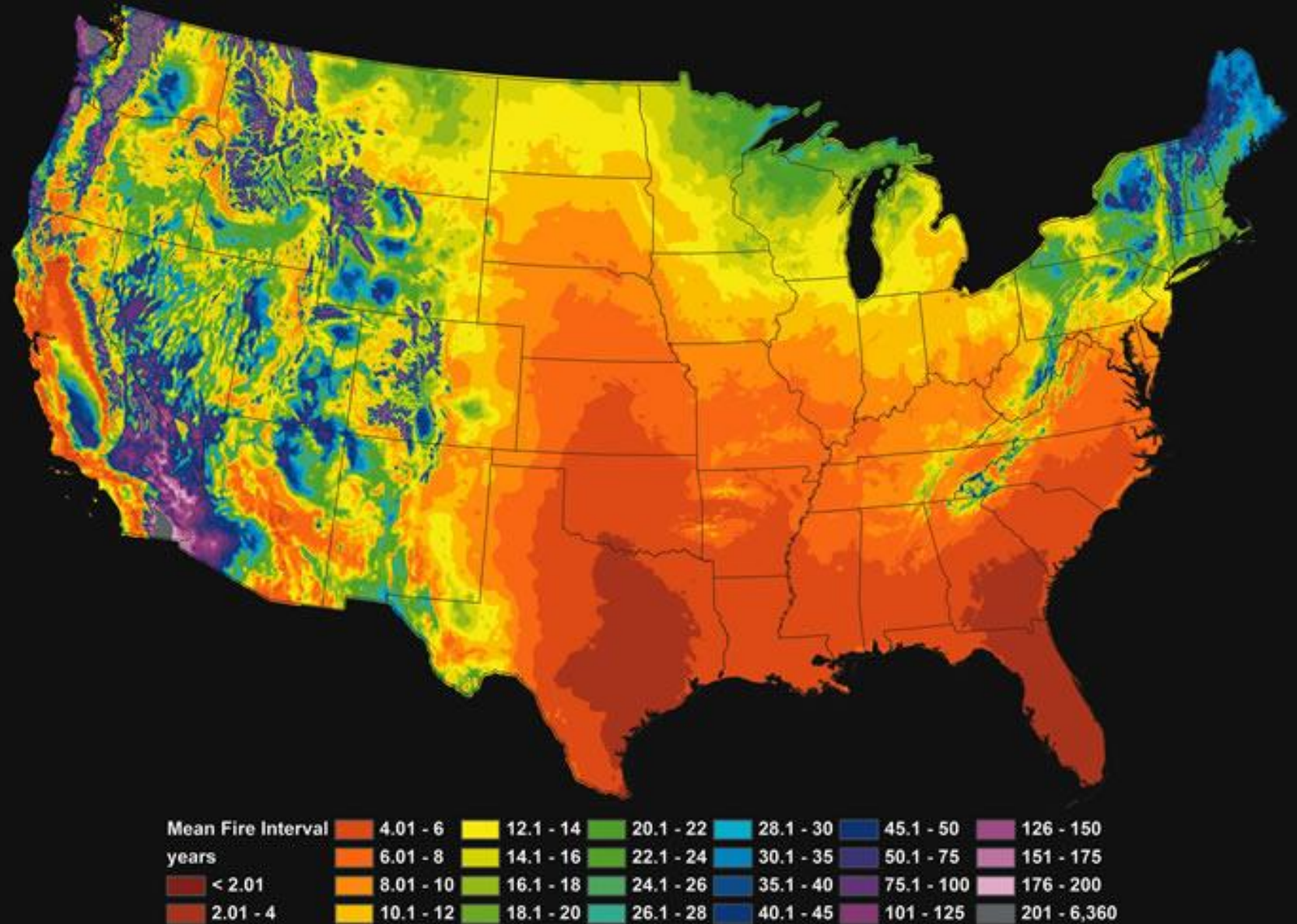
MF = most fractional branching, D-MV = dual-aware maximum-variance branching

Overall performance assessment

- Poor scalability of off-the-shelf integer optimization methods
- Poor performance of simple 2CG+IP; in comparison, strong performance improvements from upper-bounding heuristic
- **Scalability of B&P&C: high-quality solutions in large instances**

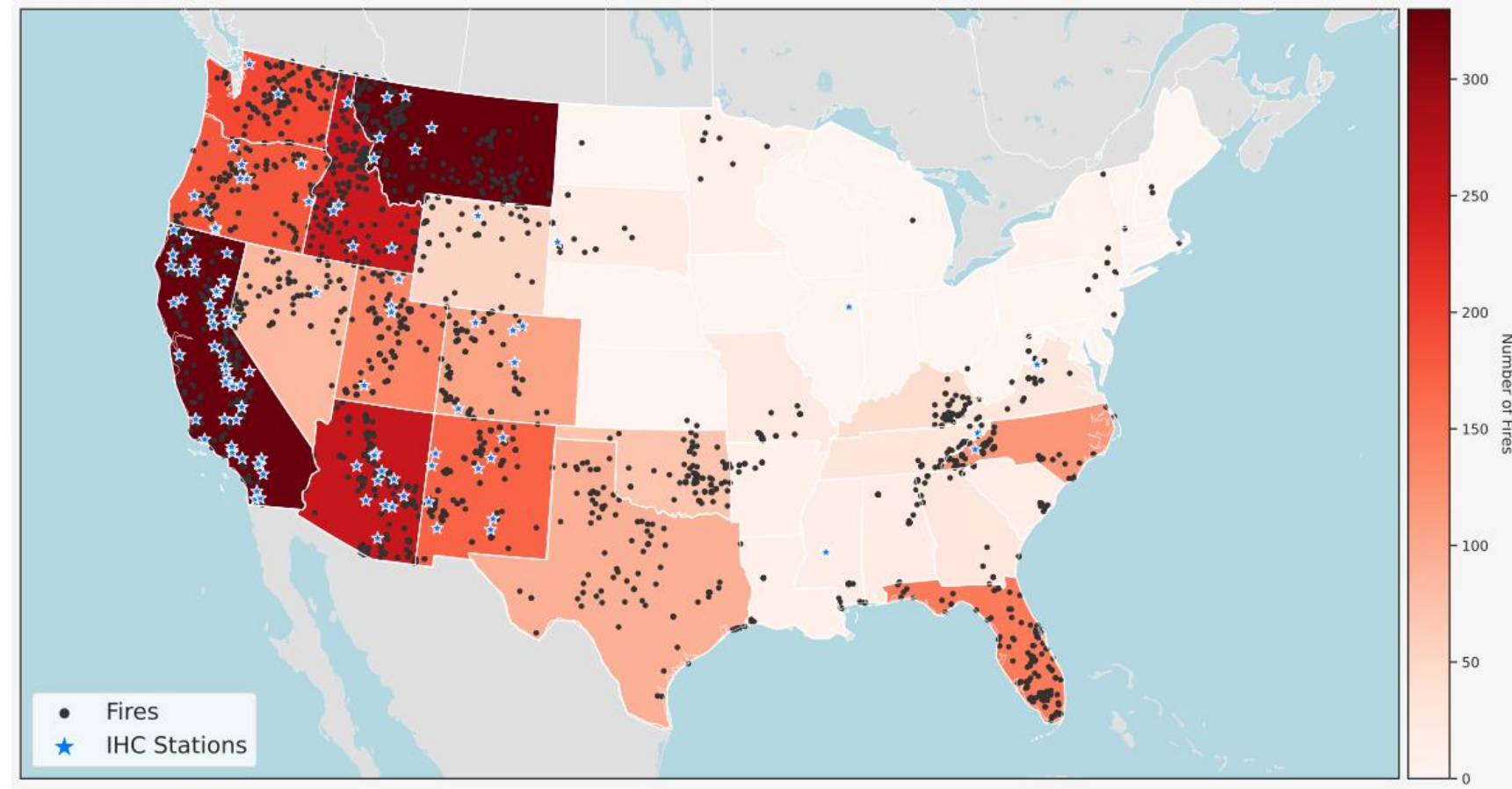
C	F	Gurobi MIP solver			2CG + IP			Root node + heuristic			Branch-and-price-and-cut		
		UB	CPU	Opt. gap	UB	CPU	Opt. gap	UB	CPU	Opt. gap	UB	CPU	Opt. gap
10	3	1.44	2	0.00%	1.44	3	0.09%	1.44	3	0.09%	1.44	3	0.00%
20	6	2.29	1,200	0.00%	2.88	34	27.8%	2.32	22	2.94%	2.29	179	0.00%
30	9	4.86	1,200	6.22%	8.91	509	99.1%	4.73	108	5.77%	4.70	1,200	2.59%
40	12	6.52	1,200	35.7%	8.74	1,200	84.1%	5.00	206	5.24%	4.95	1,200	2.84%
50	15	7.17	1,200	23.9%	513	1,200	8.83e3%	6.15	137	7.05%	5.91	1,200	1.74%
60	18	12.17	1,200	81.2%	515	1,200	7.62e3%	7.14	133	7.12%	6.97	1,200	3.76%
70	21	1.40e5	1,200	2.00e6%	9.71	1,200	39.1%	7.45	166	6.76%	7.40	1,200	5.53%

Data-driven case study

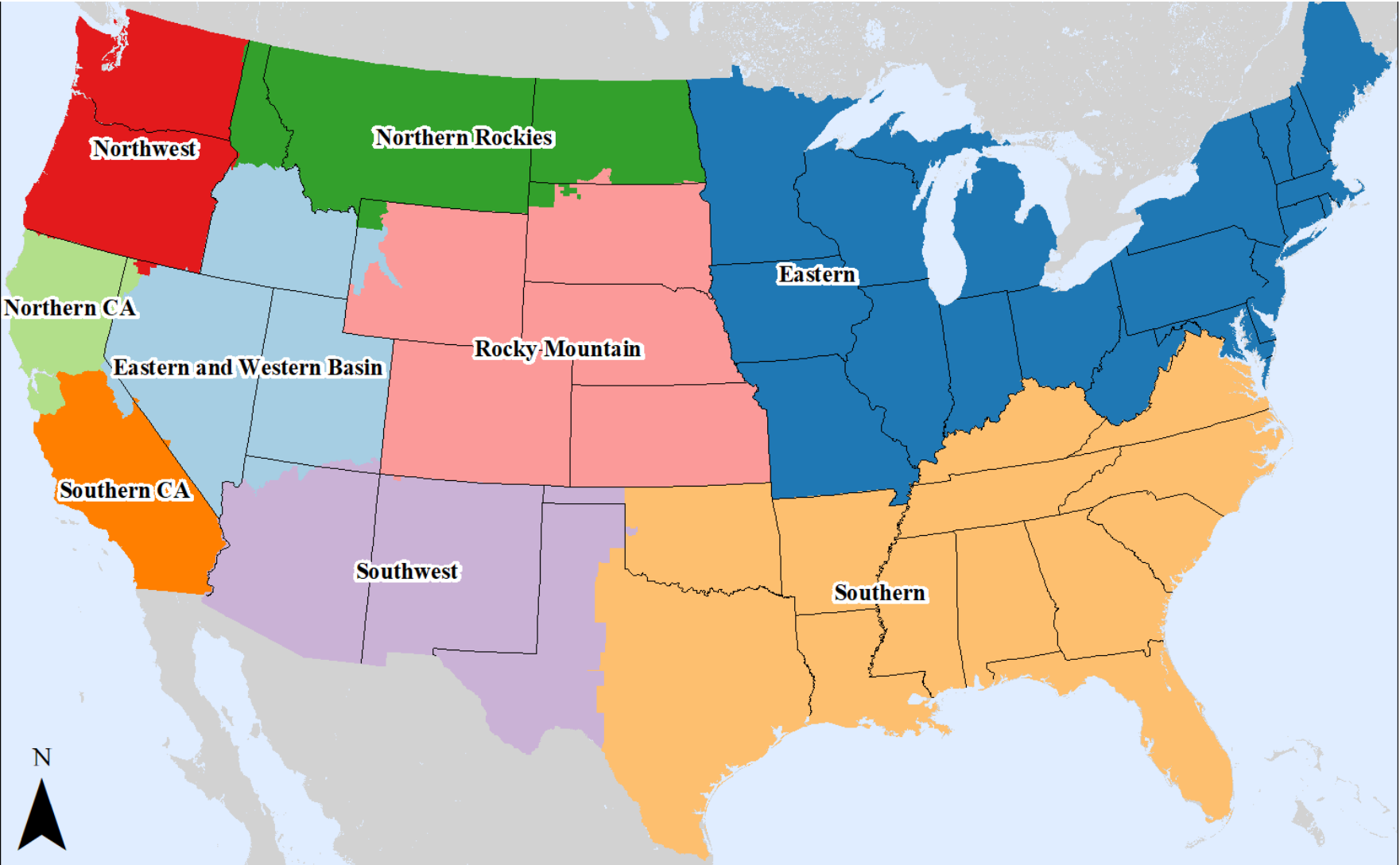


Case study setting

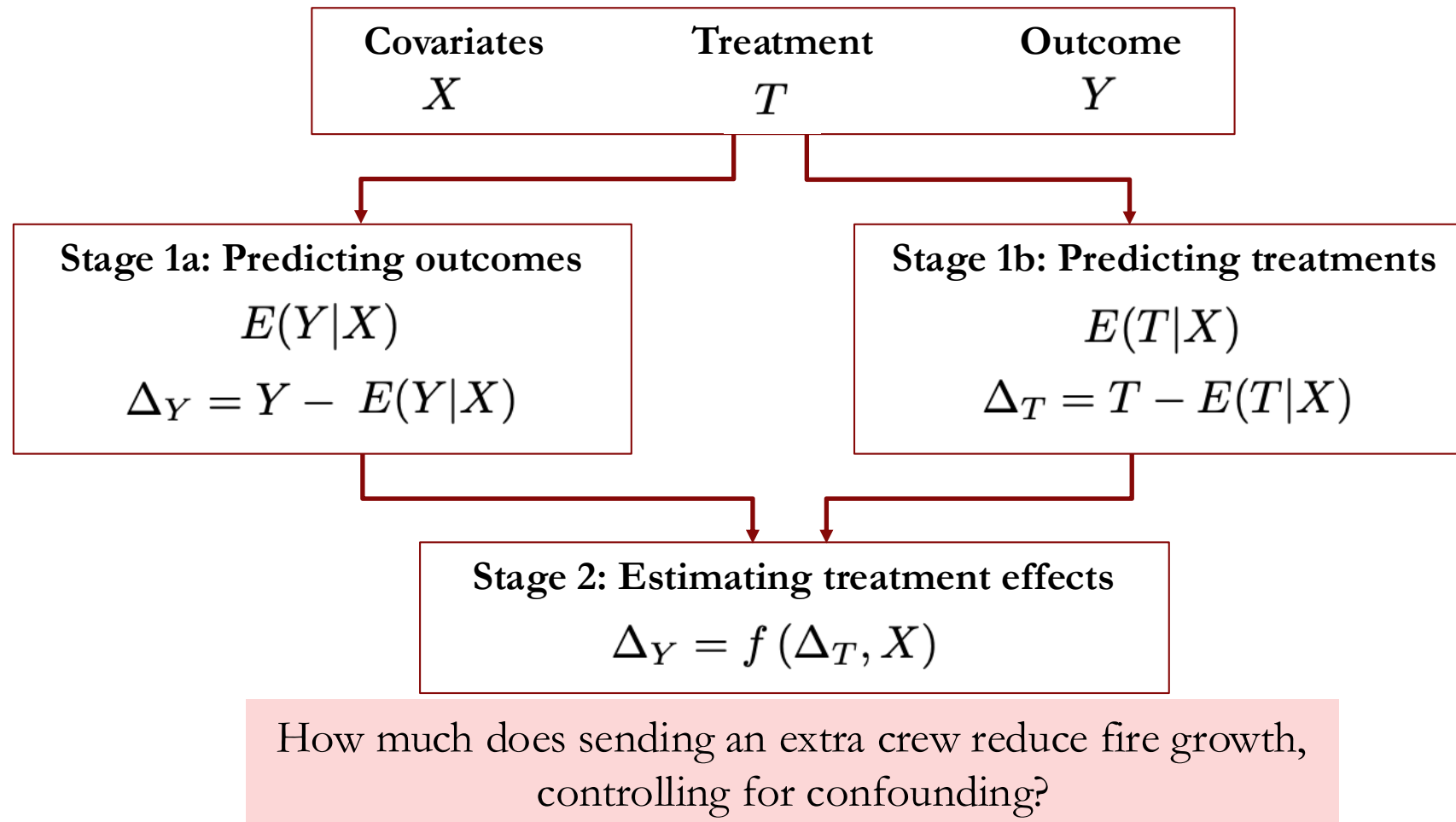
- Data-driven setup based on historical wildfire activity in the United States.
- Data on historical fires, environmental factors, and crew duties
- ~110 hot-shot crews (~ 20 firefighters/crew)
- 10–50 simultaneous fires at peak season.



US divided into Geographic Area Coordination Centers (GACCs)



Double machine learning framework



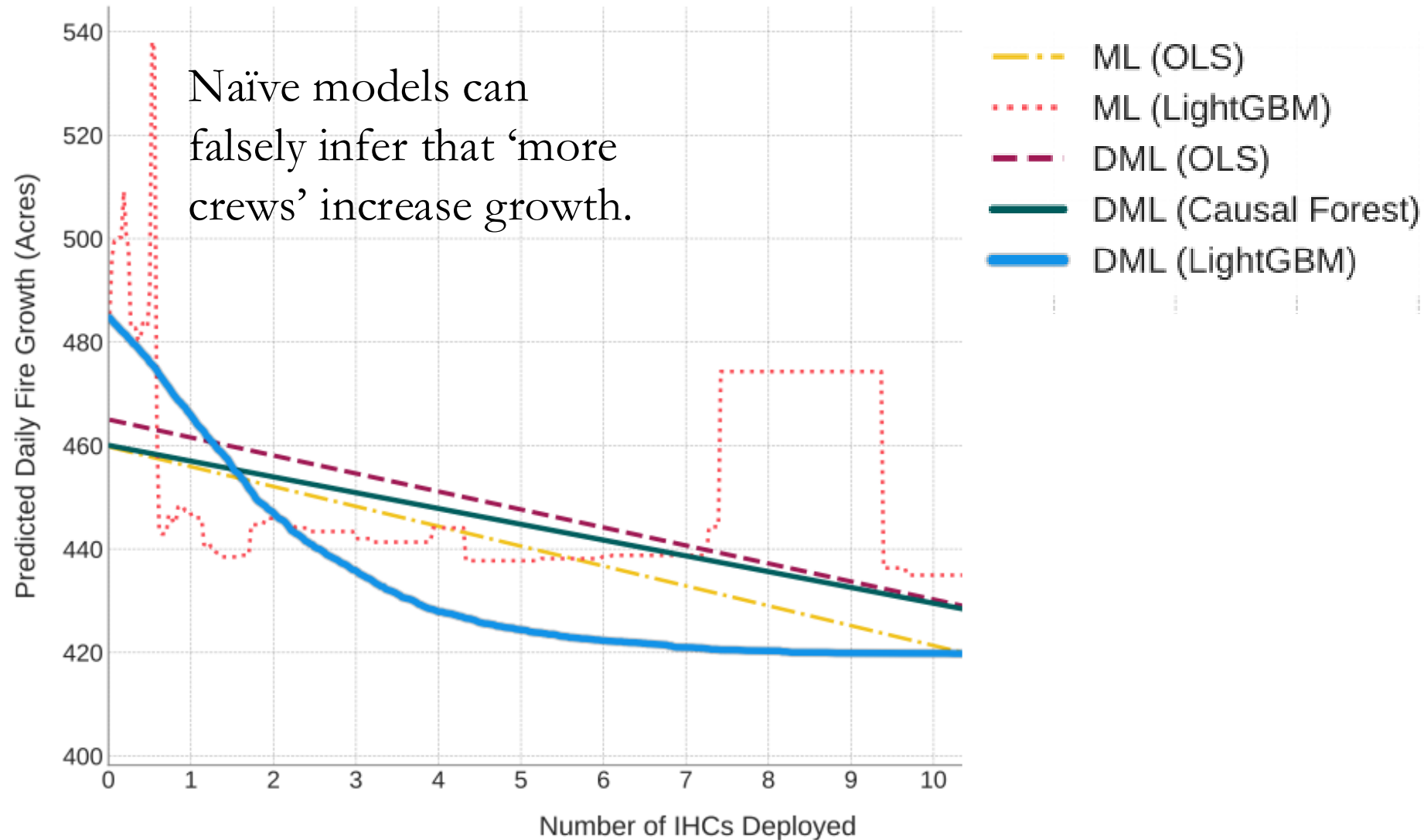
Benefits of double machine learning

1. Stronger out-of-sample performance by isolating the impact of historical suppression efforts on wildfire growth
2. Treatment effect estimates for wildfire suppression optimization

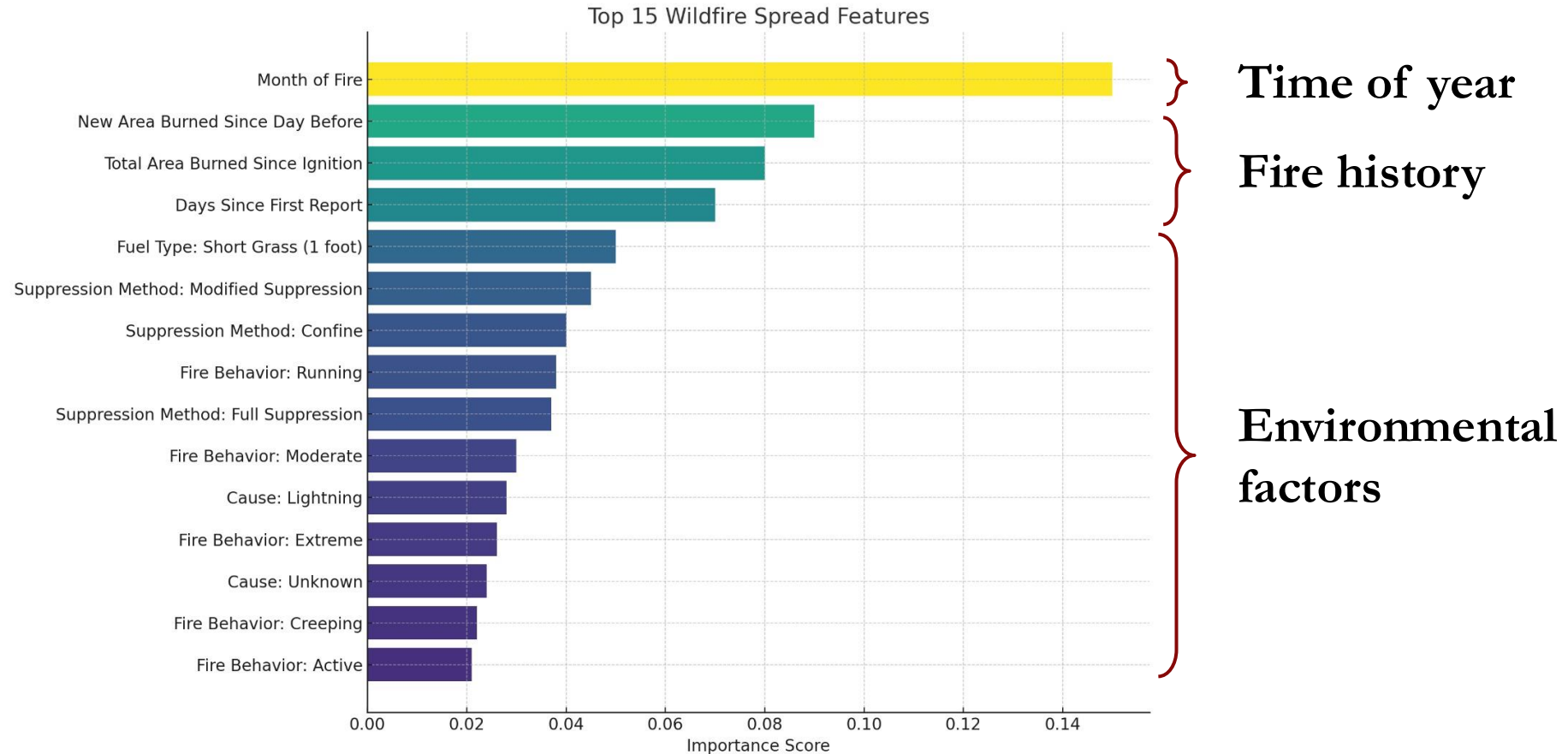
Model	RMSE	MAE	R^2	90% shortfall
<i>Single-stage machine learning</i>				
Ordinary Least Square (OLS)	599.7	424.2	0.127	1,468.5
LightGBM	584.4	405.3	0.171	1,427.8
<i>Double machine learning</i>				
LightGBM + OLS	590.3	413.9	0.154	1,400.1
LightGBM + Causal Forest	596.3	419.2	0.137	1,447.6
LightGBM + LightGBM	589.8	415.4	0.156	1,389.9

DML nomenclature: First-stage model + second-stage model

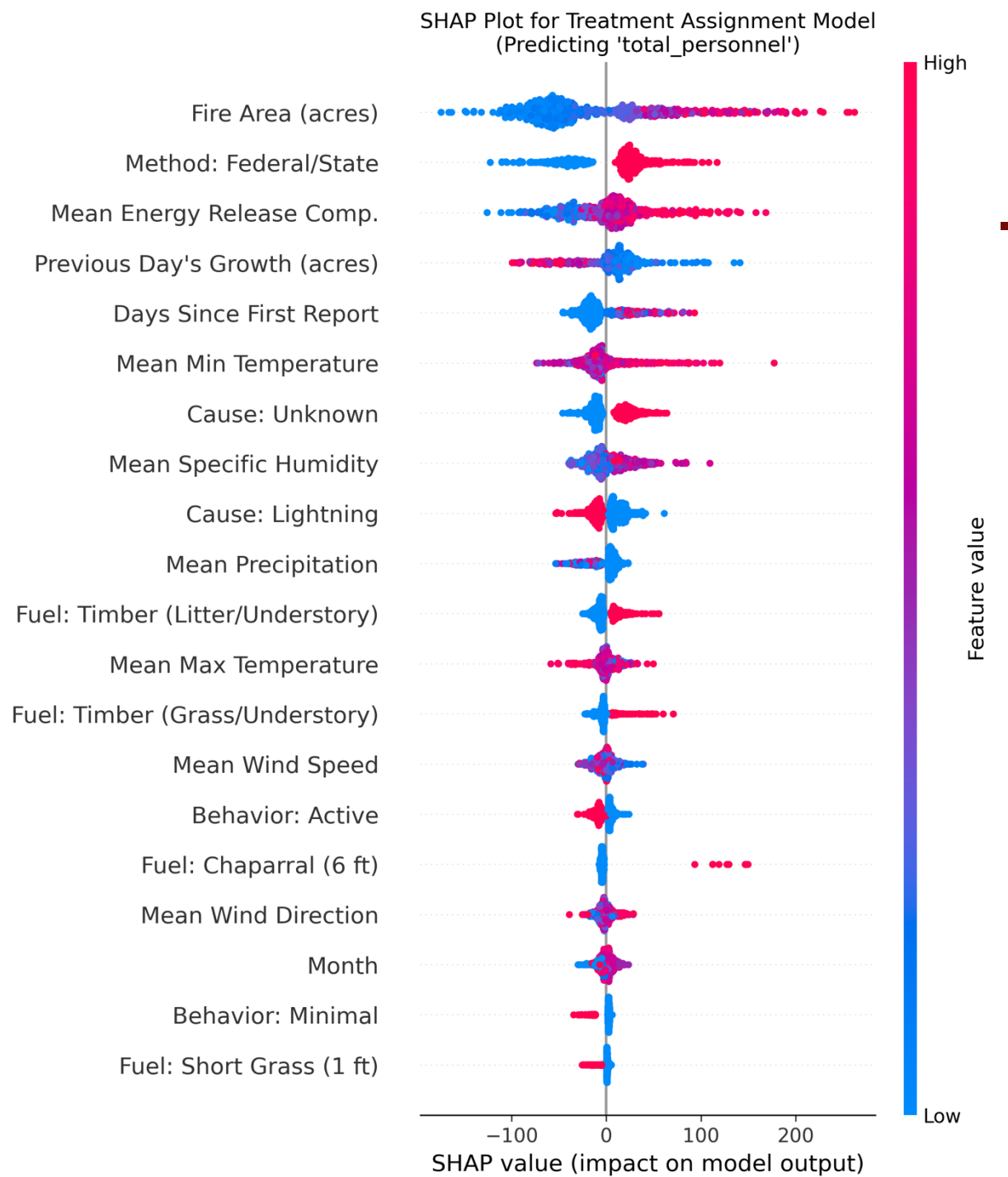
Why we want double machine learning



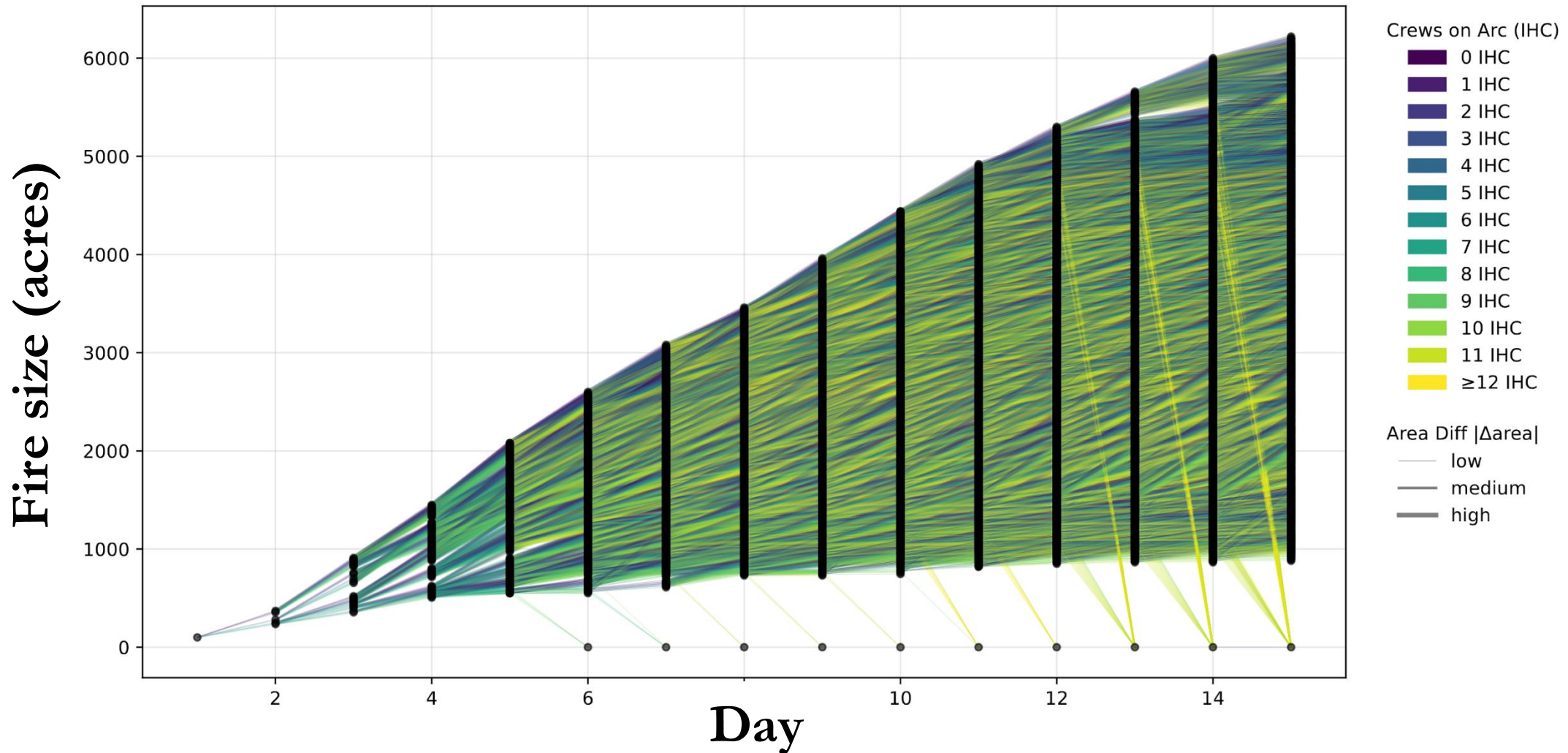
Feature importance



What drives higher personnel allocation?

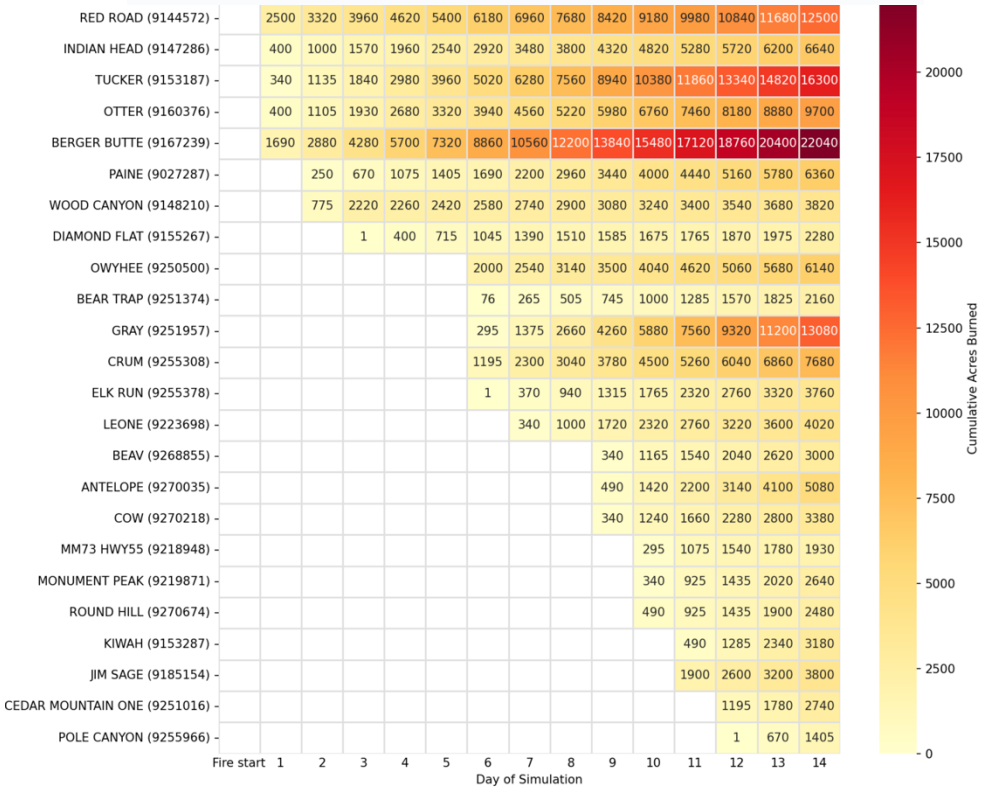


Data-driven time-state fire networks

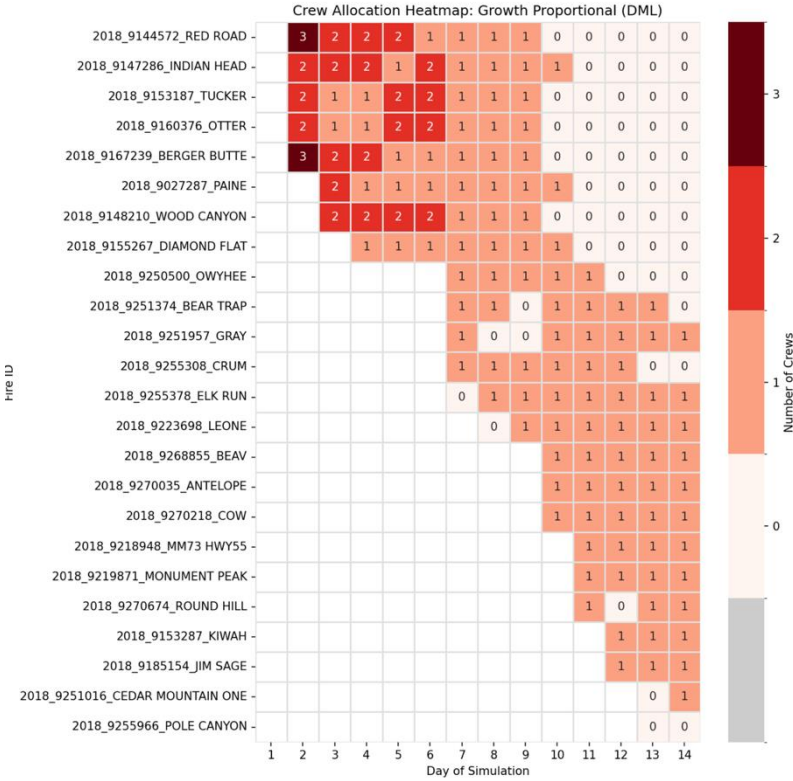


Results visualization

Wildfire progression over time

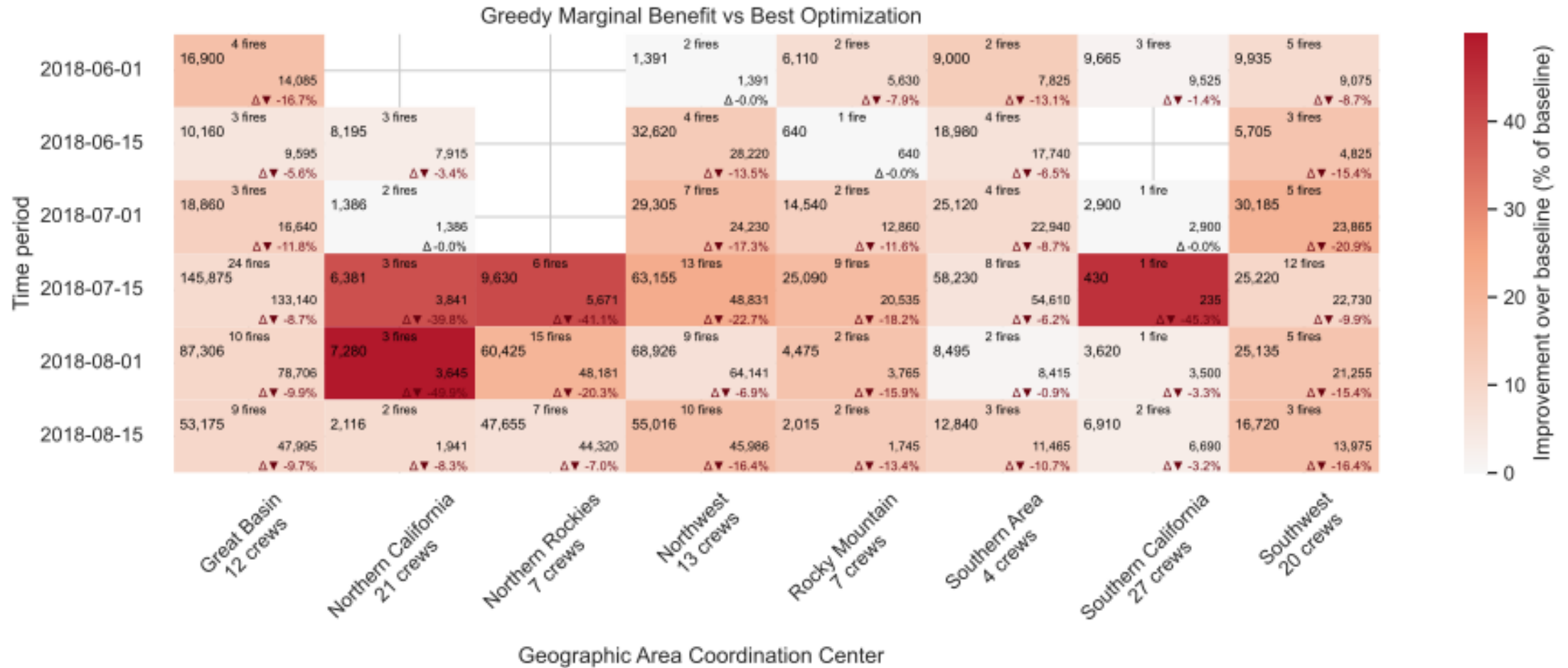


Crew assignments over time



Benefits of optimization: fine-tuning crew allocations based on wildfire impact and spatial-temporal propagation dynamics.

Optimization benefits across time and GACCs



Benefits of collaboration between GACCs

Method	Total acres burned (Jun-Aug)	Acres saved vs. no crew	% acres saved vs. no crew
No crew	1,185,981	—	—
Baseline: Crews allocated based on expected area growth	1,067,130	118,851	10.0%
Baseline: Crews allocated based on their proximity to fires	1,048,738	137,243	11.6%
Baseline: Crews allocated based on their maximum impact	1,049,777	136,204	11.5%
Optimization no coordination across GACCs	918,665	267,316	22.5%
Optimization full coordination across GACCs	681,511	504,470	42.5%

“180,000 football fields saved” thanks to coordination

Conclusion

Branch-and-price-and-cut algorithm for prescriptive wildfire analytics

Optimization
modeling

- We developed a tractable, scalable algorithm that jointly optimizes wildfire triage and crew routing.

Optimization
algorithm

- We combine prescriptive optimization with causal ML, and show strong improvements over existing methods, both in theory and practice.

Computational
results

Data-driven
case study

- This can support coordination and policy planning at the inter-agency level.



Thank you!

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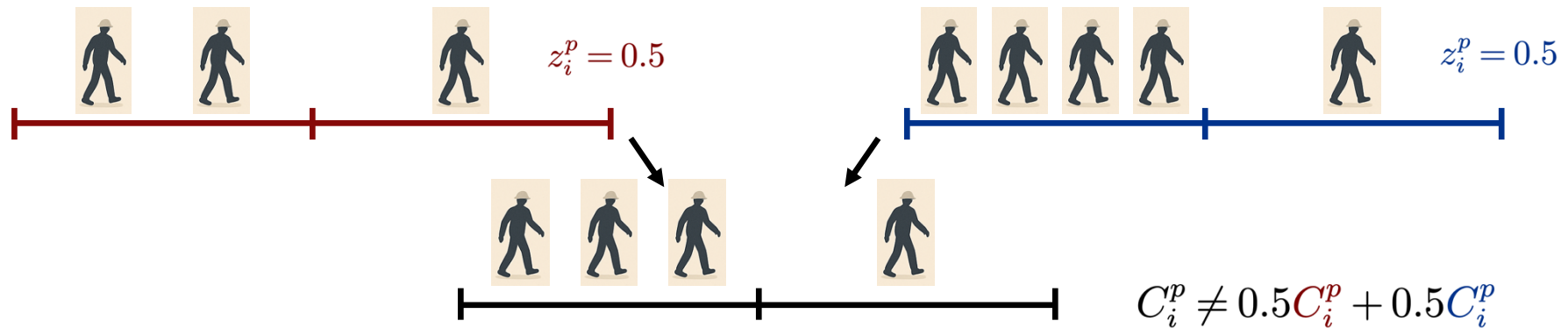
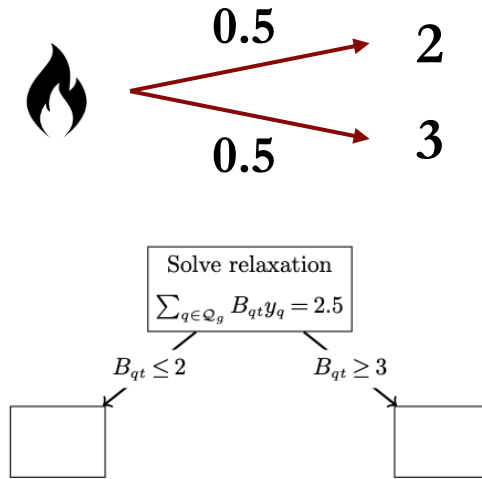
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Branching: preliminaries

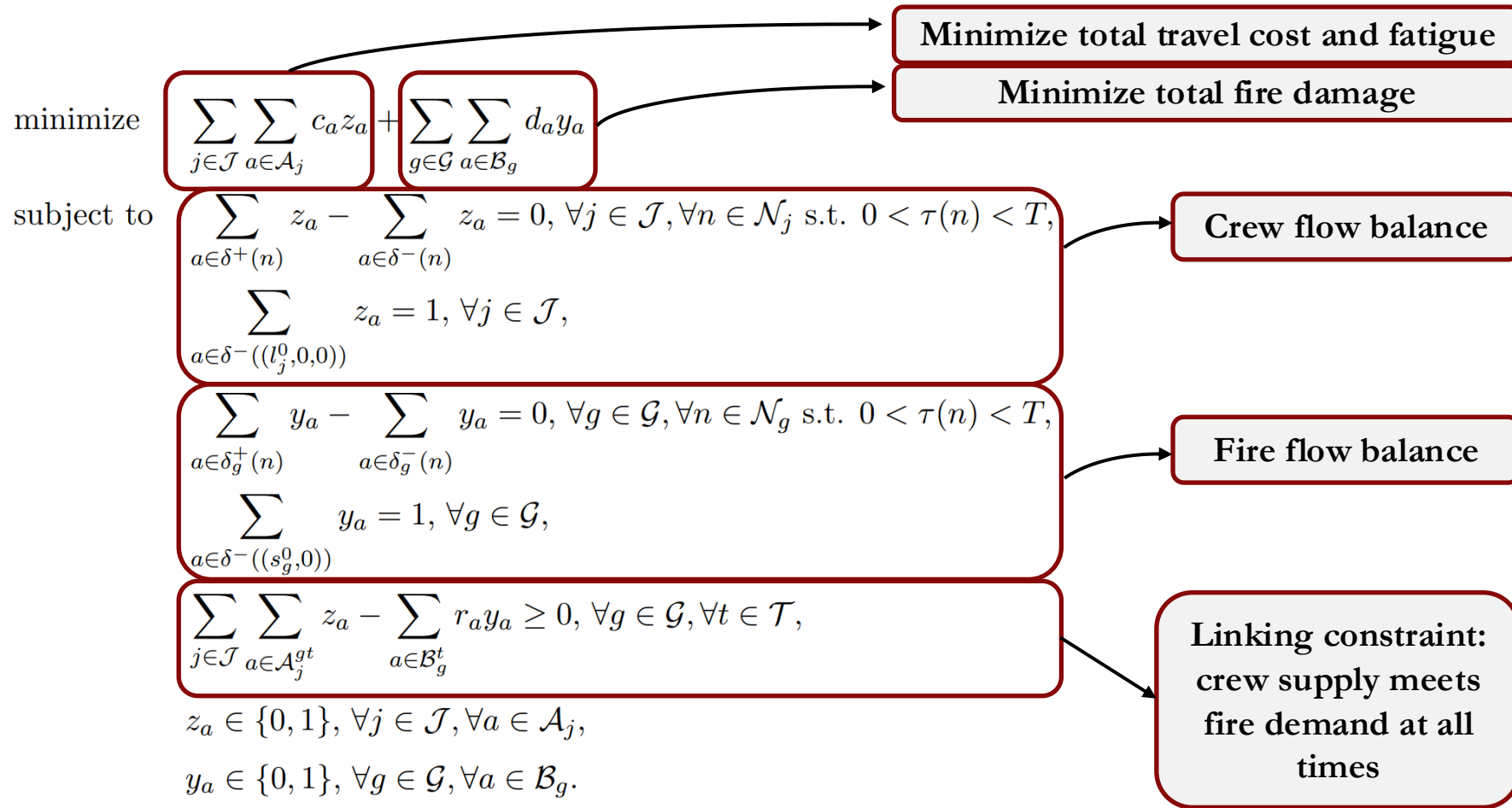
- Branching on “natural” variables: fire demand and crew assignments

$$\left(\sum_{q \in \mathcal{Q}_g} \mathbb{1}[B_{qt} > d] y_q = 0 \right) \vee \left(\sum_{q \in \mathcal{Q}_g} \mathbb{1}[B_{qt} > d] y_q = 1 \right)$$

$$\left(\sum_{p \in \mathcal{P}_j} \mathbb{1}[A_{pgt} = 1] z_p = 0 \right) \vee \left(\sum_{p \in \mathcal{P}_j} \mathbb{1}[A_{pgt} = 1] z_p = 1 \right)$$



Natural formulation

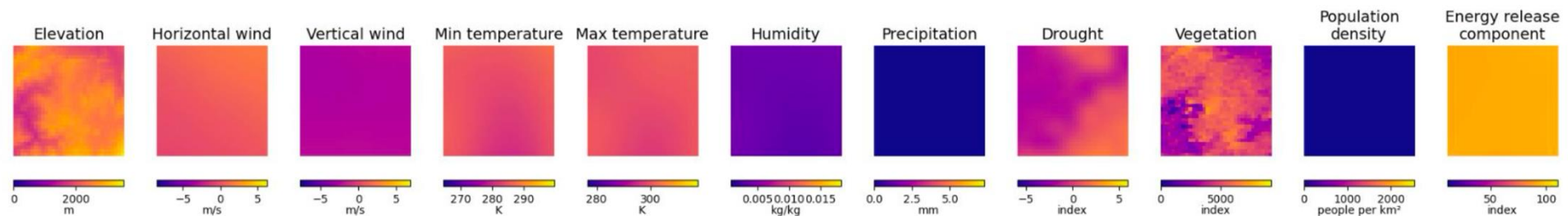


Wildfire data

- Visibility into historical wildfires and suppression efforts
 - Satellite data on daily wildfire mask [e.g., Google Earth Engine]



- Covariate information: topologic and environmental data



- New data on historical crew and machine assignments to wildfires

Toward column generation

Master problem primal

$$\begin{aligned}
 &\text{minimize} && \sum_{j \in \mathcal{J}} \sum_{p \in \mathcal{P}_j} c_p z_p + \sum_{g \in \mathcal{G}} \sum_{q \in \mathcal{Q}_g} d_q y_q \\
 &\text{subject to} && \sum_{q \in \mathcal{Q}'_g} y_q = 1, \forall g \in \mathcal{G}, \\
 &&& \sum_{p \in \mathcal{P}'_j} z_p = 1, \forall j \in \mathcal{J}, \\
 &&& \sum_{j \in \mathcal{J}} \sum_{p \in \mathcal{P}_j} A_{pgt} z_p - \sum_{q \in \mathcal{Q}_g} B_{qt} y_q \geq 0, \forall g \in \mathcal{G}, \forall t \in \mathcal{T}, \\
 &&& z_p \geq 0, \forall p \in \mathcal{P}'_j, \forall j \in \mathcal{J}, \\
 &&& y_q \geq 0, \forall q \in \mathcal{Q}'_g, \forall g \in \mathcal{G}
 \end{aligned}$$

Master problem dual

$$\begin{aligned}
 &\text{maximize} && \sum_{g \in \mathcal{G}} \sigma_g + \sum_{j \in \mathcal{J}} \pi_j \\
 &\text{subject to} && \sigma_g - \sum_{t \in \mathcal{T}} B_{qt} \rho_{gt} \leq d_q, \forall g \in \mathcal{G}, \forall q \in \mathcal{Q}'_g, \\
 &&& \pi_j + \sum_{g \in \mathcal{G}} \sum_{t \in \mathcal{T}} A_{pgt} \rho_{gt} \leq c_p, \forall j \in \mathcal{J}, \forall p \in \mathcal{P}'_j, \\
 &&& \rho_{gt} \geq 0, \forall g \in \mathcal{G}, \forall t \in \mathcal{T}
 \end{aligned}$$

The dual constraints induce a decomposition by fire and by crew

Capacitated fire demand heuristic

$$\begin{aligned}
 & \text{minimize} && \sum_{j \in \mathcal{J}} \sum_{p \in \mathcal{P}_j} c_p z_p + \sum_{g \in \mathcal{G}} \sum_{q \in \mathcal{Q}_g} d_q y_q && \bar{D}_{gt} = \left[\sum_{q \in \mathcal{Q}_g} B_{qt} y_q^* \right] \\
 & \text{subject to} && \sum_{q \in \mathcal{Q}'_g} y_q = 1, \forall g \in \mathcal{G}, \quad \sum_{q \in \mathcal{Q}'_g} \mathbb{1}[B_{qt} \leq \bar{D}_{gt}] y_q^* = 1, \forall g \in \mathcal{G}, \forall t \in \mathcal{T} \\
 & && \sum_{p \in \mathcal{P}'_j} z_p = 1, \forall j \in \mathcal{J}, \\
 & && \sum_{j \in \mathcal{J}} \sum_{p \in \mathcal{P}_j} A_{pgt} z_p - \sum_{q \in \mathcal{Q}_g} B_{qt} y_q \geq 0, \forall g \in \mathcal{G}, \forall t \in \mathcal{T}, \\
 & && z_p \geq 0, \forall p \in \mathcal{P}'_j, \forall j \in \mathcal{J}, \\
 & && y_q \geq 0, \forall q \in \mathcal{Q}'_g, \forall g \in \mathcal{G}
 \end{aligned}$$

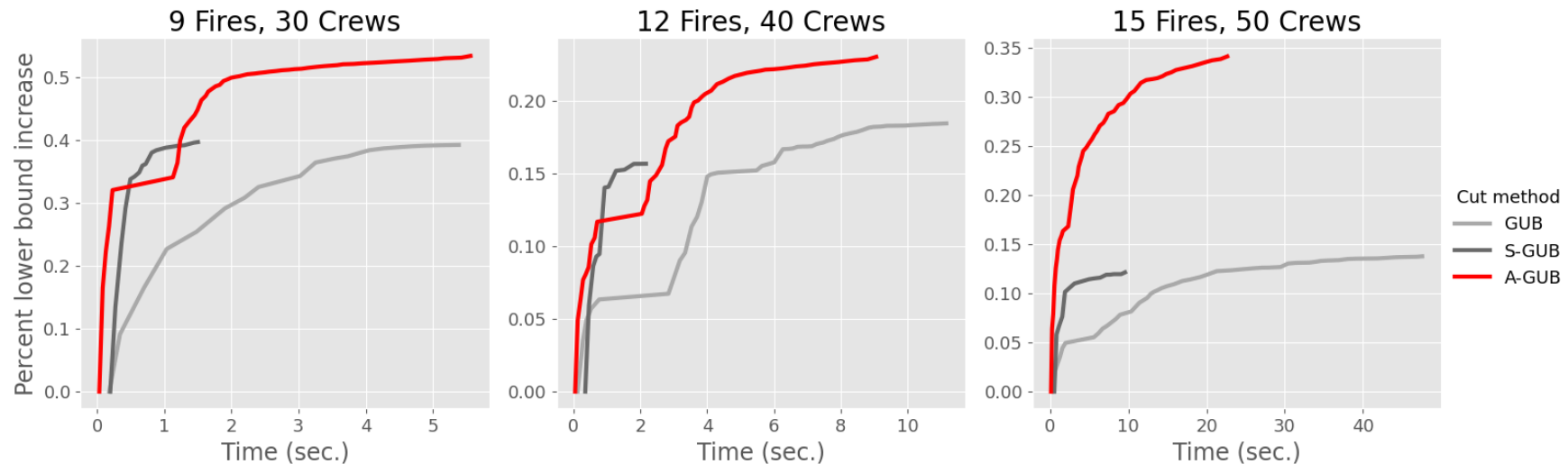
Two-sided column generation

- Convergence with a small subset of fire plans and crew routes
- Tractability improvements: 75–90% speedups vs. direct implementation of the (polynomial) natural formulation
- Scalability to large-scale problems, albeit with optimality gap

Instance size					CPU (seconds)					2CG information		
Crews	Fires	F states	F arcs	C arcs	Direct	2CG	RMP	FSP	CSP	Iter.	F cols.	C cols.
10	3	416	15,655	4,664	0.43	0.16	0.01	0.06	0.07	46	102	220
20	6	782	63,259	27,868	1.78	0.41	0.13	0.18	0.08	42	170	537
30	9	1,228	136,639	84,732	6.99	0.97	0.14	0.59	0.23	56	291	812
40	12	1,644	200,984	190,376	14.39	1.39	0.25	0.57	0.56	49	323	1,320
50	15	2,010	269,114	359,920	22.79	2.47	0.39	0.88	1.15	45	415	1,873
60	18	2,276	315,910	608,484	33.91	4.34	0.88	1.36	2.08	61	622	3,344
70	21	2,692	377,978	951,188	62.10	4.75	0.85	1.10	2.69	49	566	3,067

Benefits of augmented GUB cuts

- Augmented GUB cuts improve upon GUB cuts
 - Tighter relaxation: $>2x$ increase in lower bound improvements
 - Faster convergence: $>2x$ reductions in computational times (enabled by a cut-generating linear program)

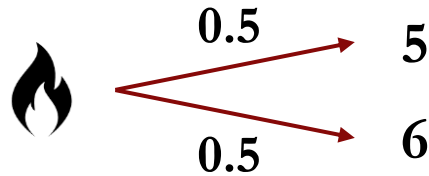


Branching rules

- Natural branching rules: fire demands and crew assignments

$$\left(\sum_{q \in \mathcal{Q}_g} \mathbb{1}[B_{qt} > d] y_q = 0 \right) \vee \left(\sum_{q \in \mathcal{Q}_g} \mathbb{1}[B_{qt} > d] y_q = 1 \right)$$

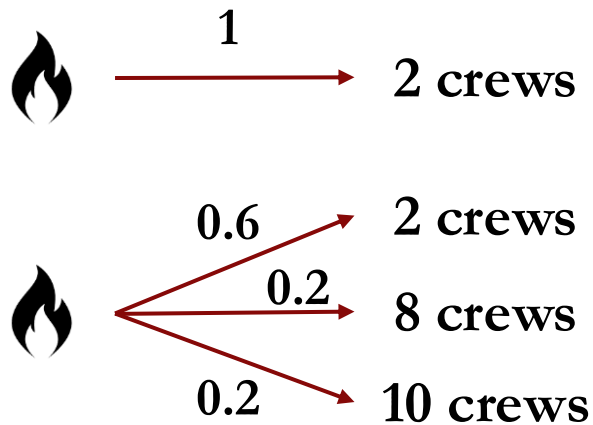
$$\left(\sum_{p \in \mathcal{P}_j} \mathbb{1}[A_{pgt} = 1] z_p = 0 \right) \vee \left(\sum_{p \in \mathcal{P}_j} \mathbb{1}[A_{pgt} = 1] z_p = 1 \right)$$



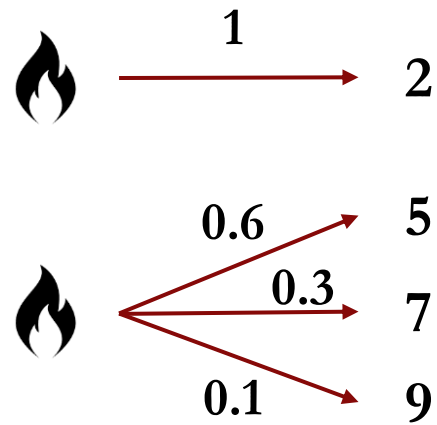
Theorem: Dual-aware max-variance branching converges finitely to integer solution, whereas fractional br $B_{qt} \leq 5$ **may** $B_{qt} \geq 6$

Cutting planes: 10-crew fire suppression plan example

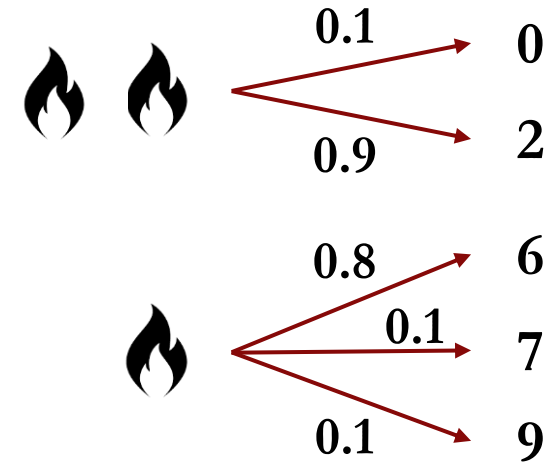
Problem: During master LP relaxation, the solver may pick fractions of different fire suppression plans.



$$\sum_{q \in Q_1} \mathbb{1}[B_{qt} \geq 2] y_q + \sum_{q \in Q_2} \mathbb{1}[B_{qt} \geq 10] y_q \leq 1$$



$$\sum_{q \in Q_1} \mathbb{1}[B_{qt} \geq 2] y_q + \sum_{q \in Q_2} \mathbb{1}[B_{qt} \geq 9] y_q \leq 1$$



$$\frac{1}{2} \sum_{q \in Q_1} \mathbb{1}[B_{qt} \geq 2] y_q + \frac{1}{2} \sum_{q \in Q_2} \mathbb{1}[B_{qt} \geq 2] y_q + \frac{1}{2} \sum_{q \in Q_3} \mathbb{1}[7 \leq B_{qt} \leq 8] y_q + \sum_{q \in Q_3} \mathbb{1}[B_{qt} \geq 9] y_q \leq 1$$

Cutting planes for LP: robust cuts

- Generalized upper-bound cover cuts (Wolsey)

$$\sum_{g \in \mathcal{G}_u} \sum_{q \in \mathcal{Q}_g} \mathbb{1}[B_{qt} \geq D_{ug}] y_q + \sum_{j \in \mathcal{J}_u} \sum_{p \in \mathcal{P}_j} \mathbb{1} \left[\sum_{g \in \mathcal{G}_u} A_{pgt} = 0 \right] z_p \leq |\mathcal{G}_u| + |\mathcal{J}_u| - 1$$

- Strengthened GUB cover cuts in the column generation context

$$\sum_{g \in \mathcal{G}_u} \sum_{q \in \mathcal{Q}_g} \mathbb{1}[B_{qt} \geq \underline{D}_{ug}] y_q + \sum_{j \in \mathcal{J}_u} \sum_{p \in \mathcal{P}_j} \mathbb{1} \left[\sum_{g \in \mathcal{G}_u} A_{pgt} = 0 \right] z_p \leq |\mathcal{G}_u| + |\mathcal{J}_u| - 1$$

- Augmented GUB cover cuts
 - Augmented GUB closure contained in GUB closure
 - Cut-generating linear program to generate augmented GUB cover cuts

$$\sum_{g \in \mathcal{G}_u} \sum_{q \in \mathcal{Q}_g} \sum_{d=0}^J \mathbb{1}[B_{qt} = d] \delta_{ugd} y_q + \sum_{j \in \mathcal{J}_u} \sum_{p \in \mathcal{P}_j} \mathbb{1} \left[\sum_{g \in \mathcal{G}_u} A_{pgt} = 0 \right] z_p \leq |\mathcal{J}_u| + K_u$$